

# On Reachability in Graphs with Bounded Independence Number

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**Abstract.** We study the reachability problem for finite directed graphs whose independence number is bounded by some constant  $k$ . This problem is a generalisation of the reachability problem for tournaments. We show that the problem is first-order definable for all  $k$ . In contrast, the reachability problems for many other types of finite graphs, including dags and trees, are not first-order definable. Also in contrast, first-order definability does not carry over to the infinite version of the problem. We prove that the number of strongly connected components in a graph with bounded independence number can be computed using  $\text{TC}^0$ -circuits, but cannot be computed using  $\text{AC}^0$ -circuits. We also study the succinct version of the problem and show that it is  $\Pi_2^P$ -complete for all  $k$ .

## 1 Introduction

One of the most fundamental problems in graph theory is the reachability problem. For this problem we are asked to decide whether there exists a path from a given source vertex  $s$  to a given target vertex  $t$  in some graph  $G$ . For finite directed graphs this problem, which will be denoted  $\text{REACH}$  in the following, is well-known to be  $\text{NL}$ -complete [12, 13]. It is thus easy from a computational point of view and efficient parallel algorithms are known for it. The complexity of the reachability problem drops if we restrict the type of graphs for which we try to solve it. The reachability problem  $\text{REACH}_u$  for finite undirected graphs is  $\text{SL}$ -complete [15] and thus presumably easier to solve. The even more restricted problem  $\text{REACH}_{\text{forest}}$  for undirected forests and the problem  $\text{REACH}_{\text{out} \leq 1}$  for directed graphs in which all vertices have out-degree at most 1 are  $\text{L}$ -complete [2].

In this paper we study the reachability problem for finite directed graphs whose independence number is bounded by some constant  $k$ . The independence number  $\alpha(G)$  of a graph  $G$  is the maximum number of vertices that can be picked from  $G$  such that there is no edge between any two of these vertices. Thus we study the languages  $\text{REACH}_{\alpha \leq k} := \text{REACH} \cap \{\langle G, s, t \rangle \mid \alpha(G) \leq k\}$  for constant  $k$ , where  $\langle \rangle$  denotes a standard binary encoding. We show that, somewhat surprisingly,  $\text{REACH}_{\alpha \leq k}$  is first-order definable for all  $k$ .

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First-order definability means the following. Let  $\tau = (E^2, s, t)$  be the signature of directed graphs with two distinguished vertices. The binary relation symbol  $E$  represents an edge relation and the constant symbols  $s$  and  $t$  represent a source and a target vertex. We show that for each  $k$  there exists a first-order formula  $\phi_{\text{reach}, \alpha \leq k}$  over the signature  $\tau$  for which the following holds: for all *finite* directed graphs  $G = (V, E)$  and all  $s, t \in V$  the  $\tau$ -structure  $(V, E, s, t)$  is a model of  $\phi_{\text{reach}, \alpha \leq k}$  iff  $\alpha(G) \leq k$  and there is path from  $s$  to  $t$  in  $G$ . The formulas will neither require an ordering on the universe nor the bit predicate [11].

The most prominent examples of graphs with bounded independence number are *tournaments* [18, 20], which are directed graphs with exactly one edge between any two vertices. Their independence number is 1. Conditions for strong connectedness of tournaments (and thus, implicitly, for reachability) were proven in [9], but these conditions yield weaker bounds on the complexity of the reachability problem for tournaments than those shown in the present paper. A different example of graphs with bounded independence number, studied in [4], are directed graphs  $G = (V, E)$  whose underlying undirected graph is claw-free, i.e., does not contain the  $K_{1,m}$  for some constant  $m$ , and whose minimum degree is at least  $|V|/3$ . Their independence number is at most  $3m - 3$ .

Languages whose descriptive complexity is first-order are known to be very simple from a computational point of view. They can be decided by a family of  $\text{AC}^0$ -circuits (constant depth circuits) and also in constant parallel time on concurrent-read, concurrent-write parallel random access machines [16]. Since it is known that L-hard sets cannot be first-order definable [1, 6],  $\text{REACH}_{\alpha \leq k}$  is (unconditionally) easier to solve than  $\text{REACH}$ ,  $\text{REACH}_{\text{u}}$ , and  $\text{REACH}_{\text{forest}}$ .

A problem closely related to the reachability problem is the problem of identifying the strongly connected components of a graph. We show that  $\text{TC}^0$ -circuits (constant depth circuits with threshold gates) can count the strongly connected components in graphs with bounded independence number, but  $\text{AC}^0$ -circuits cannot—not even in tournaments.

In hardware design one is often concerned with succinctly represented graphs, which are given implicitly via a program or a circuit that decides the edge relation of the graph. Papadimitriou, Yannakakis, and Wagner [19, 23, 24] have shown that the problems  $\text{SUCCINCT-REACH}$ ,  $\text{SUCCINCT-REACH}_{\text{u}}$ ,  $\text{SUCCINCT-REACH}_{\text{forest}}$ , and  $\text{SUCCINCT-REACH}_{\text{out} \leq 1}$  are PSPACE-complete. Opposed to this, we show that  $\text{SUCCINCT-REACH}_{\alpha \leq k}$  is  $\Pi_2^P$ -complete for all  $k$ .

Our results apply only to finite graphs. Let  $\text{REACH}_{\alpha \leq k}^\infty$  be the class of all triples  $(G, s, t)$  such that  $G$  is a (possibly infinite) directed graph with  $\alpha(G) \leq k$  in which there is a path from  $s$  to  $t$ . We show that there does not exist a set of first-order formulas (not even an uncountable one) whose class of models is exactly  $\text{REACH}_{\alpha \leq k}^\infty$  for some  $k$ .

This paper is organised as follows. In Section 2 we study graph-theoretic definitions and results and prove a general theorem that shows how the independence number of a graph is connected to its different domination numbers. We believe this theorem to be of independent interest. In Section 3 we show that the problem  $\text{REACH}_{\alpha \leq k}$  is first-order definable, by explicitly giving a defining

formula. In Section 4 we study the circuit complexity of counting the number of strongly connected components in a graph. In Sections 5 we study the infinite version of our problem and in Section 6 the succinct version.

## 2 Graph-Theoretic Definitions and Results

In this section we first give definitions of basic graph-theoretic concepts. Then we prove a generalisation of the so-called lion king lemma, see Theorem 2.2. At the end of the section we prove Theorem 2.3, which will be the crucial building block of our first-order definition of  $\text{REACH}_{\alpha \leq k}$ .

A *graph* is a nonempty set  $V$  of vertices together with a set  $E \subseteq V \times V$  of directed edges. The *out-degree* of a vertex  $u$  is the number of vertices  $v$  with  $(u, v) \in E$ . A *path of length  $\ell$*  in a graph  $G = (V, E)$  is a sequence  $v_0, \dots, v_\ell$  of vertices with  $(v_i, v_{i+1}) \in E$  for  $i \in \{0, \dots, \ell - 1\}$ . A vertex  $t$  is *reachable* from a vertex  $s$  if there is a path from  $s$  to  $t$ . A *strongly connected component* is a maximal vertex set  $U \subseteq V$  such that every vertex in  $U$  is reachable from every other vertex in  $U$ . A set  $U \subseteq V$  is an *independent set* if there is no edge in  $E$  connecting vertices in  $U$ . The maximal size of independent sets in  $G$  is its *independence number*  $\alpha(G)$ . For  $i \in \mathbb{N}$ , a vertex  $u \in V$  is said to  *$i$ -dominate* a vertex  $v \in V$  if there is a directed path from  $u$  to  $v$  of length at most  $i$ . Let  $\text{dom}_i(U)$  denote the set of vertices that are  $i$ -dominated by vertices in  $U$ . A set  $U \subseteq V$  is an  *$i$ -dominating set* for  $G$  if  $\text{dom}_i(U) = V$ . The  *$i$ -domination number*  $\beta_i(G)$  is the minimal size of an  $i$ -dominating set for  $G$ . A *tournament* is a graph with exactly one edge between any two different vertices and  $(v, v) \notin E$  for all  $v \in V$ . Note that tournaments have independence number 1.

**Lemma 2.1.** *Let  $G = (V, E)$  be a finite graph,  $n := |V|$ ,  $\alpha := \alpha(G)$ . Then  $G$  has at least  $\binom{n}{2} / \binom{\alpha+1}{2}$  edges and there exists a vertex with out-degree at least  $(n-1) / 2^{\binom{\alpha+1}{2}}$ .*

*Proof.* The number of  $(\alpha+1)$ -element subsets of  $V$  is  $\binom{n}{\alpha+1}$ . Every such set contains two vertices linked by an edge. Every such edge is in  $\binom{n-2}{\alpha-1}$  different  $(\alpha+1)$ -element subsets of  $V$ . Therefore there are at least  $\binom{n}{\alpha+1} / \binom{n-2}{\alpha-1} = \binom{n}{2} / \binom{\alpha+1}{2}$  edges in  $G$ . This also shows that the average out-degree in  $G$  is at least  $\binom{n}{2} / n^{\binom{\alpha+1}{2}} = (n-1) / 2^{\binom{\alpha+1}{2}}$  and one vertex has at least this out-degree.  $\square$

Turán [21], referenced in [22], gives an exact formula for the minimal number of edges in a graph as a function of the graph's independence number. However, the simple bound from the above lemma will be more appropriate for our purposes.

**Theorem 2.2.** *Let  $G = (V, E)$  be a finite graph,  $n := |V|$ ,  $\alpha := \alpha(G)$ . Then  $\beta_1(G) \leq \lceil \log_c n \rceil$  and  $\beta_2(G) \leq \alpha$ , where  $c = (\alpha^2 + \alpha) / (\alpha^2 + \alpha - 1)$ .*

*Proof.* We iteratively construct a 1-dominating set  $D_1$  for  $G$  of size at most  $\lceil \log_c n \rceil$ . In each step we put a vertex  $v_i$  into  $D_1$  that dominates as many vertices as possible of the subset  $V_i \subseteq V$  not dominated so far. Formally, set  $V_0 := V$

and for  $i \geq 1$ , as long as  $V_{i-1}$  is not empty, choose a vertex  $v_i \in V_{i-1}$  such that  $V_i := V_{i-1} \setminus \text{dom}_1(\{v_i\})$  is as small as possible. Let  $i_{\max}$  be the first  $i$  such that  $V_i$  is empty. By Lemma 2.1 the out-degree of  $v_i$  is at least  $(|V_{i-1}| - 1) / 2^{\binom{\alpha+1}{2}}$  and thus

$$\begin{aligned} |V_i| &\leq |V_{i-1}| - 1 - \frac{|V_{i-1}| - 1}{2^{\binom{\alpha+1}{2}}} < |V_{i-1}| - \frac{|V_{i-1}|}{2^{\binom{\alpha+1}{2}}} \\ &= |V_{i-1}| \left(1 - \frac{1}{2^{\binom{\alpha+1}{2}}}\right) = |V_{i-1}| \left(\frac{\alpha^2 + \alpha - 1}{\alpha^2 + \alpha}\right) = \frac{|V_{i-1}|}{c}. \end{aligned}$$

This shows that the size of  $V_i$  decreases by at least the factor  $c$  in each step. Thus after at most  $\lceil \log_c n \rceil$  iterations the set  $V_i$  is empty and  $D_1 := \{v_1, \dots, v_{i_{\max}}\}$  is the desired 1-dominating set.

We next construct a 2-dominating set  $D_2$  of size at most  $\alpha$  by removing superfluous vertices from  $D_1$ . Formally, let  $W_{i_{\max}} := \{v_{i_{\max}}\}$  and let  $W_{i-1} := W_i$  if  $v_i \in \text{dom}_1(W_i)$ , and  $W_{i-1} := W_i \cup \{v_i\}$  otherwise. Clearly,  $D_2 := W_1$  is a 2-dominating set. To prove  $|D_2| \leq \alpha$ , assume that  $D_2$  contains at least  $\alpha + 1$  vertices  $v_{i_1}, \dots, v_{i_{\alpha+1}} \in D_1$ . Since these vertices cannot be independent, there must exist indices  $i_r$  and  $i_s$  such that  $(v_{i_r}, v_{i_s}) \in E$ . By construction of the set  $D_1$ , this can only be the case if  $i_s > i_r$ . But then  $v_{i_r} \notin D_2$  by construction of  $W_{i_r}$ , a contradiction.  $\square$

For tournaments  $G$ , Theorem 2.2 yields  $\beta_1(G) \leq \log_2(n)$  and  $\beta_2(G) = 1$ . The first result was first proved by Megiddo and Vishkin in [17], where it was used to show that the dominating set problem for tournaments is not NP-complete, unless  $\text{NP} \subseteq \text{DTIME}(n^{O(\log n)})$ . The second result is also known as the lion king lemma, which was first noticed by Landau in [14] in the study of animal societies, where the dominance relations on prides of lions form tournaments. It has applications in the study of P-selective sets [10] and many other fields.

**Theorem 2.3.** *Let  $G = (V, E)$  be a finite graph,  $n := |V|$ ,  $\alpha := \alpha(G)$ ,  $c := (\alpha^2 + \alpha) / (\alpha^2 + \alpha - 1)$ , and  $s, t \in V$ . Then the following statements are equivalent:*

1. *There is no path from  $s$  to  $t$  in  $G$ .*
2. *There is a subset  $D_1 \subseteq V$  with  $|D_1| \leq \lceil \log_c n \rceil$  such that  $\text{dom}_1(D_1)$  is closed under reachability,  $s \in \text{dom}_1(D_1)$  and  $t \notin \text{dom}_1(D_1)$ .*
3. *There is a subset  $D_2 \subseteq V$  with  $|D_2| \leq \alpha$  such that  $\text{dom}_2(D_2)$  is closed under reachability,  $s \in \text{dom}_2(D_2)$  and  $t \notin \text{dom}_2(D_2)$ .*

*Proof.* Both 2 and 3 imply 1, since no path starting at a vertex  $s$  inside a set that closed is under reachability can ‘leave’ this set to arrive at a vertex  $t$  outside this set. To show that 1 implies 2, consider the set  $S$  of vertices reachable from  $s$  in  $G$ . Then  $S$  is closed under reachability,  $s \in S$  and  $t \notin S$ . The induced graph  $G' := (S, E \cap (S \times S))$  also has independence number at most  $\alpha$ . Therefore, by Theorem 2.2, the graph  $G'$  has a 1-dominating set  $D_1$  of size at most  $\lceil \log_c n \rceil$ . To show that 1 implies 3, consider the same graph  $G'$  once more. By Theorem 2.2 it also has a 2-dominating set  $D_2$  of size at most  $\alpha$ .  $\square$

### 3 First-Order Definability of the Problem

In this section we show that reachability in graphs with bounded independence number is first-order definable. We start with a review of some basic notions from descriptive complexity theory.

We use the *signature* or *vocabulary*  $\tau = (E^2, s, t)$ . It consists of a binary relation symbol  $E$ , representing an edge relation, and constant symbols  $s$  and  $t$ , representing a source and a target vertex. A  $\tau$ -*structure* is a tuple  $(V, E, s, t)$  such that  $E \subseteq V \times V$  and  $s, t \in V$ . We do not distinguish notationally between the symbols in the signature and their interpretation in a structure, because it is always clear from the context which of the two meanings is intended. The standardised binary code of a finite  $\tau$ -structure  $(V, E, s, t)$  will be denoted  $\langle V, E, s, t \rangle$ . A set  $A$  of codes of finite  $\tau$ -structures is *first-order definable* if there exists a first-order formula  $\phi$  over the signature  $\tau$  such that for all finite  $\tau$ -structures  $(V, E, s, t)$  we have  $(V, E, s, t) \models \phi$  iff  $\langle V, E, s, t \rangle \in A$ .

**Theorem 3.1.** *For each  $k$ ,  $\text{REACH}_{\alpha \leq k}$  is first-order definable.*

*Proof.* Let  $k \geq 1$  be fixed. We give a stepwise construction of a formula  $\phi_{\text{reach}, \alpha \leq k}$  such that  $(V, E, s, t) \models \phi_{\text{reach}, \alpha \leq k}$  iff  $\langle V, E, s, t \rangle \in \text{REACH}_{\alpha \leq k}$ . Roughly spoken, the formula  $\phi_{\text{reach}, \alpha \leq k}$  will say ‘ $\alpha(G) \leq k$  and it is not the case that condition 3 of Theorem 2.3 holds for  $s$  and  $t$ ’.

Let  $\phi_{\text{distinct}}(v_1, \dots, v_k) \equiv \bigwedge_{i \neq j} [v_i \neq v_j]$ . This formula expresses that vertices are distinct. The property ‘ $\alpha(G) \leq k$ ’ can be expressed as follows:

$$\phi_{\alpha \leq k} \equiv (\forall v_1, \dots, v_{k+1}) \left[ \phi_{\text{distinct}}(v_1, \dots, v_{k+1}) \rightarrow \bigvee_{i \neq j} E(v_i, v_j) \right].$$

The next two formulas express that a vertex  $v$ , respectively a set  $\{v_1, \dots, v_m\}$  of vertices, 2-dominates a vertex  $u$ :

$$\begin{aligned} \phi_{2\text{-dom}}(v, u) &\equiv v = u \vee E(v, u) \vee (\exists z) [E(v, z) \wedge E(z, u)], \\ \phi_{2\text{-dom}}(v_1, \dots, v_m, u) &\equiv \phi_{2\text{-dom}}(v_1, u) \vee \dots \vee \phi_{2\text{-dom}}(v_m, u). \end{aligned}$$

Since  $\beta_2(G) \leq \alpha(G) \leq k$ , condition 3 of Theorem 2.3 can be expressed as follows:

$$\begin{aligned} \phi_{\text{condition}} &\equiv (\exists v_1, \dots, v_k) \\ &\left[ \phi_{2\text{-dom}}(v_1, \dots, v_k, s) \wedge \neg \phi_{2\text{-dom}}(v_1, \dots, v_k, t) \wedge \right. \\ &\quad \left. (\forall u, v) [(\phi_{2\text{-dom}}(v_1, \dots, v_k, u) \wedge \neg \phi_{2\text{-dom}}(v_1, \dots, v_k, v)) \rightarrow \neg E(u, v)] \right]. \end{aligned}$$

The desired formula  $\phi_{\text{reach}, \alpha \leq k}$  is given by  $\phi_{\alpha \leq k} \wedge \neg \phi_{\text{condition}}$ .  $\square$

Note that the formula  $\phi_{\text{reach}, \alpha \leq k}$  constructed in the proof has quantifier alternation depth three, beginning with a universal quantifier.

Theorem 3.1 be easily extended to the following larger class of graphs: define the *r-independence number*  $\alpha_r(G)$  of a graph  $G$  as the maximal size of an  $r$ -independent set in  $G$ , which is a vertex subset such that there is no path of length at most  $r$  between any two different vertices in this subset. Then reachability in graphs with  $\alpha_r(G) \leq k$  is first-order definable for all  $k, r \in \mathbb{N}$ .

## 4 Circuit Complexity of the Problem

In this section we study the circuit complexity of the problem  $\text{REACH}_{\alpha \leq k}$ , as well as the complexity of counting the number of strongly connected components in a graph with bounded independence number. We show that this number can be computed using  $\text{TC}^0$ -circuits, but cannot be computed using  $\text{AC}^0$ -circuits.

A family  $\mathcal{C} = (C_n)_{n \in \mathbb{N}}$  of circuits is a *family of  $\text{AC}^0$ -circuits* if each  $C_n$  has  $n$  input gates, their size is bounded by a polynomial in  $n$ , their depth is bounded by a constant, and each  $C_n$  consist of unbounded fan-in/fan-out and-, or-, and not-gates. For  $\text{TC}^0$ -circuits we also allow threshold gates, whose output is 1 if the number of 1's at the input exceeds some threshold. For  $x \in \{0, 1\}^n$  we write  $\mathcal{C}(x)$  for the output produced by  $C_n$  on input  $x$ . The output may be a bitstring since we allow multiple output gates. A circuit family  $\mathcal{C}$  *decides* a set  $A \subseteq \{0, 1\}^*$ , respectively *computes* a function  $f: \{0, 1\}^* \rightarrow \{0, 1\}^*$ , if for all  $x \in \{0, 1\}^*$  we have  $x \in A$  iff  $\mathcal{C}(x) = 1$ , respectively  $f(x) = \mathcal{C}(x)$ .

As shown by Lindell [16], every first-order definable set can be decided by  $\text{AC}^0$ -circuits. In particular, by Theorem 3.1 there exists, for each  $k$ , an  $\text{AC}^0$ -circuit family  $\mathcal{C}^k$  that decides  $\text{REACH}_{\alpha \leq k}$ . We now sketch how these families can be used to decrease the average case complexity of  $\text{REACH}$ , which is L-hard and thus does not have  $\text{AC}^0$ -circuits [1, 6]. Suppose there exists a constant  $k$  for which we expect  $\alpha(G) \leq k$  to hold with high probability for input graphs  $G$ . Then whenever  $\alpha(G) \leq k$  holds, we can use  $\mathcal{C}^k$  to decide in constant depth whether there is a path from  $s$  to  $t$ . For graphs with  $\alpha(G) > k$  we use a slow standard reachability circuit to decide whether such a path exists. If the probability of  $\alpha(G) \leq k$  is sufficiently large, the preprocessing will decrease the average time taken by the circuit to produce its output.

A problem closely related to the reachability problem is the problem of counting strongly connected components. The following theorem pinpoints the exact circuit complexity of this counting problem for graphs with bounded independence number. Let  $\zeta_{\alpha \leq k}: \{0, 1\}^* \rightarrow \{0, 1\}^*$  be the function that maps the code  $\langle G \rangle$  of a graph  $G$  to the binary representation of the number of strongly connected components in  $G$  if  $\alpha(G) \leq k$ , and that maps  $\langle G \rangle$  to 0 if  $\alpha(G) > k$ .

**Theorem 4.1.** *For each  $k$ ,  $\zeta_{\alpha \leq k}$  can be computed by  $\text{TC}^0$ -circuits, but not by  $\text{AC}^0$ -circuits.*

*Proof.* Let  $k$  be fixed. Let  $\phi_{\text{reach}, \alpha \leq k}(u, v)$  be the formula with two free variables expressing that  $v$  is reachable from  $u$  and that the underlying graph has independence number at most  $k$ . It is obtained from  $\phi_{\text{reach}, \alpha \leq k}$  from the proof of Theorem 3.1 by replacing the constant symbols  $s$  and  $t$  by variables  $u$  and  $v$ . Consider the formula

$$\phi_{\text{rep}}(v) \equiv (\forall u)[u < v \rightarrow (\neg \phi_{\text{reach}, \alpha \leq k}(u, v) \vee \neg \phi_{\text{reach}, \alpha \leq k}(v, u))],$$

where ' $<$ ' is a relation that is interpreted as a total ordering of the set of vertices.

For a graph  $G$  with  $\alpha(G) \leq k$ , the formula  $\phi_{\text{rep}}(v)$  will be true exactly for the smallest members (with respect to the ordering  $<$ ) of each strongly connected

component. Thus, the number of vertices  $v$  for which  $\phi_{rep}(v)$  holds is exactly the number of strongly connected components in  $G$ . Since  $\phi_{rep}$  is a first-order formula, there exists a family of  $AC^0$ -circuits that maps  $\langle \{v_1, \dots, v_n\}, E \rangle$  to a bitstring in which the  $i$ -th position is 1 iff  $(\{v_1, \dots, v_n\}, E) \models \phi_{rep}(v_i)$ . Since the number of 1's in this bitstring can be computed in constant depth using threshold gates,  $\zeta_{\alpha \leq k}$  can be computed by  $TC^0$ -circuits.

Next, for the sake of contradiction, assume that there exists an  $AC^0$ -circuit family  $\mathcal{C}$  that computes  $\zeta_{\alpha \leq k}$ . We construct an  $AC^0$ -circuit for the parity function, contradicting the results of Ajtai et al. [1, 6]. Let a bitstring  $b = b_1 \dots b_n$  be given as input. Define a tournament  $G = (\{1, \dots, n+1\}, E)$  as follows: for  $i+1 < j$  there is an edge from  $j$  to  $i$ ; for  $i+1 = j$  there is an edge from  $j$  to  $i$  if  $b_i = 1$ ; otherwise there is an edge from  $i$  to  $j$ . If  $b$  contains no 1's, the tournament will form one big circle, thus having just one strongly connected component. Every additional 1 in  $b$  adds one strongly connected component. The parity of  $b$  is thus given by the toggled least-significant bit of  $\mathcal{C}(\langle G \rangle)$ .  $\square$

## 5 Infinite Version of the Problem

In this section we study the class  $REACH_{\alpha \leq k}^\infty$  and show that the results of Section 3 on the first-order definability of  $REACH_{\alpha \leq k}$  do not carry over to  $REACH_{\alpha \leq k}^\infty$ . This class contains all triples  $(G, s, t)$  such that  $G$  is a (possibly infinite) graph with  $\alpha(G) \leq k$  in which there is a path from  $s$  to  $t$ . We start with a review of the relevant notions from model theory.

Let  $\tau$  be a signature. A class  $K$  of  $\tau$ -structures is called *elementary (over finite structures)* if there exists a first-order formula  $\phi$  over  $\tau$  such that for every (finite)  $\tau$ -structure  $\mathcal{A}$  we have  $\mathcal{A} \models \phi$  iff  $\mathcal{A} \in K$ . (Some authors use ‘finitely axiomatisable’ instead of ‘elementary’.) A class  $K$  of  $\tau$ -structures is  $\Delta$ -*elementary* if there exists a set  $\Phi$  of first-order formulas over  $\tau$  such that for every  $\tau$ -structure  $\mathcal{A}$  we have  $\mathcal{A} \models \Phi$  iff  $\mathcal{A} \in K$ .

**Fact 5.1 (Compactness Theorem).** *Let  $\Phi$  be a set of first-order formulas such that every finite  $\Phi_0 \subseteq \Phi$  has a model. Then  $\Phi$  has a model.*

With these definitions, Theorem 3.1 simply states that  $REACH_{\alpha \leq k}^\infty$  is elementary over finite structures for all  $k$ . The below proof that  $REACH_{\alpha \leq k}^\infty$  is not even  $\Delta$ -elementary follows the standard pattern of proofs applying the compactness theorem. The only essential part is the construction of appropriate model graphs for finite subsets of a hypothetical axiomatisation of  $REACH_{\alpha \leq k}^\infty$ .

**Theorem 5.2.**  *$REACH_{\alpha \leq k}^\infty$  is not  $\Delta$ -elementary for any  $k$ .*

*Proof.* Assume that there exists a set  $\Phi$  of first-order formulas with  $(V, E, s, t) \models \Phi$  iff  $(V, E, s, t) \in REACH_{\alpha \leq k}^\infty$ . For each  $n \in \mathbb{N}$  define the following formula  $\psi_n$ , which is fulfilled by a graph iff there is a path of length  $n$  from  $s$  to  $t$ .

$$\psi_n \equiv (\exists v_1, \dots, v_{n-1}) [E(s, v_1) \wedge E(v_1, v_2) \wedge \dots \wedge E(v_{n-2}, v_{n-1}) \wedge E(v_{n-1}, t)].$$

Consider the set  $\Psi := \Phi \cup \{\neg\psi_1, \neg\psi_2, \neg\psi_3, \dots\}$ . We claim that every finite  $\Psi_0 \subseteq \Psi$  has a model  $(V, E, s, t)$ . To see this, let  $n$  be large enough such that for all  $i \geq n$  we have  $\neg\psi_i \notin \Psi_0$  and define a graph  $G = (V, E)$  by  $V := \{1, \dots, n+1\}$  and  $(i, j) \in E$  iff  $j \leq i+1$ . Then  $\alpha(G) = 1 \leq k$  and the shortest path from  $s := 1$  to  $t := n+1$  has length  $n$ . Thus  $(V, E, s, t)$  is a model of  $\Psi_0$ .

Since every finite subset of  $\Psi$  has a model,  $\Psi$  has a model  $(V, E, s, t)$  by the compactness theorem. Since this model fulfills  $\neg\psi_n$  for all  $n$ , there can be no path of finite length from  $s$  to  $t$  in  $G = (V, E)$ . Thus  $\Phi$  has a model that is not an element of  $\text{REACH}_{\alpha \leq k}^\infty$ .  $\square$

## 6 Succinct Version of the Problem

In this section we study succinctly represented graphs. Such graphs are given implicitly via a description in some description language. Since succinct representations allow one to encode large graphs into small codes, checking properties is (provably) harder for succinctly represented graphs than for graphs coded in the usual way. Papadimitriou et al. [19, 24] have shown that most interesting problems for succinctly represented graphs are PSPACE-complete or even NEXP-complete. The following formalisation of succinct graph representations is due to Galperin and Wigderson [7], but others are also possible [24, 8].

**Definition 6.1.** A succinct representation of a graph  $G = (\{0, 1\}^n, E)$  is a  $2n$ -input circuit  $C$  such that for all  $u, v \in \{0, 1\}^n$  we have  $(u, v) \in E$  iff  $C(uv) = 1$ .

The circuit tells us for any two vertices of the graph whether there is a directed edge between them or not. Note that there is no need to bound the size of  $C$ .

**Definition 6.2.** Let  $A \subseteq \{\langle G, s, t \rangle \mid G = (V, E) \text{ is a finite graph, } s, t \in V\}$ . Then  $\text{SUCCINCT-}A$  is the set of all codes  $\langle C, s, t \rangle$  such that  $C$  is a succinct representation of a graph  $G$  with  $\langle G, s, t \rangle \in A$ .

**Theorem 6.3.** For each  $k$ ,  $\text{SUCCINCT-REACH}_{\alpha \leq k}$  is  $\Pi_2^P$ -complete.

*Proof.* We first show  $\text{SUCCINCT-REACH}_{\alpha \leq k} \in \Pi_2^P$ . Let  $\langle C, s, t \rangle$  be an input and let  $C$  represent a graph  $G = (V, E)$  with  $V = \{0, 1\}^n$ . Note that  $\log_2 |V| = n$ . We first check whether  $\alpha(G) \leq k$ , which can easily be done using a coNP-machine. We then check whether there is path from  $s$  to  $t$  in  $G$ . By Theorem 2.3 this is case iff for all sets  $D_1 \subseteq \{0, 1\}^n$  of size at most  $\beta_1(G)$  either  $s \notin \text{dom}_1(D_1)$  or  $t \in \text{dom}_1(D_1)$  or  $\text{dom}_1(D_1)$  is not closed under reachability, i.e., there exist vertices  $u \in \text{dom}_1(D_1)$  and  $v \in \{0, 1\}^n \setminus \text{dom}_1(D_1)$  such that  $C(uv) = 1$ . Since  $\beta_1(G) \leq \lceil \log_c 2^n \rceil \leq \lceil n / \log_2 c \rceil$ , the size of the  $D_1$ 's that need to be checked is linear in  $n$ . Thus the 'for all ... exists ...' test is a  $\Pi_2^P$ -algorithm, since a membership test for the set  $\text{dom}_1(D_1)$  can be performed in polynomial time.

We now prove that even the reachability problem  $\text{SUCCINCT-REACH}_{\text{tourn}}$  for tournaments is  $\Pi_2^P$ -hard. Let  $L \in \Pi_2^P$  be any language. By the quantifier characterisation of the polynomial hierarchy [25] there exists a polynomial time decidable ternary relation  $R$  and a constant  $c$  such that

$$L = \{x \mid (\forall y, |y| = |x|^c)(\exists z, |z| = |x|^c)[R(x, y, z)]\}.$$



We construct a reduction from  $L$  to  $\text{SUCCINCT-REACH}_{\text{tourn}}$ . On input  $x$  we construct, in polynomial time, a circuit  $C$  and two bitstrings  $s, t$  such that  $x \in L$  iff  $\langle C, s, t \rangle \in \text{SUCCINCT-REACH}_{\text{tourn}}$ . Let  $n$  denote the length of  $x$  and let  $\ell := n^c$ .

The circuit  $C$  will represent a highly structured tournament  $G$  of exponential size. The vertex set of  $G$  is  $V = \{0, 1\}^{2\ell+1}$ . Each vertex  $v \in V$  can be split into a ‘y-component’  $y \in \{0, 1\}^{\ell+1}$  and a ‘z-component’  $z \in \{0, 1\}^\ell$  with  $yz = v$ . All vertices that have the same y-component form a *level*. All vertices on the same level are connected such that they form a strongly connected subtournament of  $G$ . We say a level is *above* another level if its y-component is lexicographically larger than the other level’s y-component.

Edges between different levels generally point ‘downwards’, i. e., from higher levels to lower levels. The only exception are edges between a vertex with y-component  $0\tilde{y}$  with  $\tilde{y} \in \{0, 1\}^\ell$  and the vertex with the same z-component on the level directly above. Such an edge points ‘upwards’ iff  $R(x, \tilde{y}, z)$ . The source is any vertex on the bottom level, the target is any vertex on level  $10^\ell$ .

The graph  $G$  is a tournament and the representing circuit  $C$  can be constructed in polynomial time. From each level  $y$  one can go (at best) only one level higher to the next level  $y'$ , since all edges between non-neighbouring levels point downwards. Since all vertices on the same level are connected, if one can reach a vertex  $v$  on level  $0\tilde{y}$ , one can reach a vertex on the level directly above iff  $R(x, y', z)$  holds for some  $z \in \{0, 1\}^\ell$ . So in order to get from the source to the target, for all  $\tilde{y} \in \{0, 1\}^\ell$  there must exist a  $z \in \{0, 1\}^\ell$  such that  $R(x, \tilde{y}, z)$ .  $\square$

## 7 Conclusion and Open Problems

We showed that the complexity of the reachability problem for graphs with bounded independence number is lower than the complexity of the corresponding problem for, say, forests. However, we did not claim that is also easier to *actually find a path* in a tournament. While it is easily seen that there is a function in FL that maps every forest to a path from the first to the last vertex, provided such a path exists, we do not know whether such a function exists for tournaments. We recommend this problem for further research.

We do not know whether the three levels of quantifier alternation in the first-order formula for  $\text{REACH}_{\alpha \leq k}$  are necessary, but conjecture that this is the case. Since we do not refer to an ordering relation in our first-order formula, it seems promising to use an Ehrenfeucht-Fraïssé game [3, 5] to prove this.

In the succinct setting, we proved that the problem  $\text{SUCCINCT-REACH}_{\alpha \leq k}$  is  $\Pi_2^P$ -complete for all  $k$ . Opposed to this, for  $r > 1$  our arguments only show  $\text{SUCCINCT-REACH}_{\alpha_r \leq k} \in \Pi_3^P$ . In particular, we would like to know the exact complexity of  $\text{SUCCINCT-REACH}_{\alpha_2 \leq 1}$ .

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